Packing Plane Spanning Trees and Paths in Complete Geometric Graphs[☆]

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Abstract

We consider the following question: How many edge-disjoint plane spanning trees are contained in a complete geometric graph GK_n on any set S of n points in general position in the plane? We show that this number is in $\Omega(\sqrt{n})$. Further, we consider variants of this problem by bounding the diameter and the degree of the trees (in particular considering spanning paths).

1. Introduction

A geometric graph G = (S, E) consists of a set of vertices S, which are points in general position in the plane, and a set of edges E which are straight-line connections between two of these points. A long-standing open question is the following: Does every complete geometric graph with 2n vertices have a partition of its edges into n plane spanning trees? For complete convex geometric graphs (where all vertices lie in convex position), a positive answer to this question follows from a result by Bernhart and Kainen [6] (see [7]). Bose et al. [7] gave a characterization of the solutions; for complete convex geometric graphs all spanning trees can, but do not have to, be spanning paths. They also described

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a sufficient condition generalizing the convex case and considered a relaxation where the trees are not required to be spanning.

We consider a closely related question: How many edge-disjoint plane spanning trees are contained in a complete geometric graph GK_n on any set S of n points in general position in the plane? In Section 2 we show how to combine a construction by Bose et al. [7] with a result by Aronov et al. [5] to prove that GK_n contains $\Omega(\sqrt{n})$ edge-disjoint plane spanning trees. Furthermore, if the convex hull of S contains h vertices then we can argue that GK_n contains at least $\lfloor \frac{h}{2} \rfloor$ edge-disjoint plane spanning trees. We also show that GK_n contains at least 2 plane edge-disjoint spanning trees if $n \geq 4$ and at least 3 edge-disjoint spanning trees if $n \geq 6$.

In Section 3 we study the special case of spanning paths. In particular, we first consider the "regular wheel configuration", that is, a set of points W_{2n} which consists of 2n-1 points regularly spaced on a circle C and a point at the center of C. Let GW_{2n} be the complete geometric graph on W_{2n} . We can argue that GW_{2n} can be partitioned into n spanning trees. But surprisingly, if $n \geq 3$ then none of these trees can be paths. If the "hub" of the wheel is moved close to the convex hull, then all n spanning trees can be paths. This raises the following interesting open question: When does this transition happen and is it gradual? That is, does the number of spanning paths increase whenever the hub passes over certain diagonals? Note, though, that spanning paths can of course be used in packings which are not partitions. More specifically, GW_{2n} always contains n-1 spanning paths. Only when we ask for a complete partition of the edges we cannot use even a single spanning path.

On the positive side we argue that GK_n contains at least 2 edge-disjoint spanning paths if $n \geq 4$. Obviously it would be desirable to extend our argument to 3 or more paths or to develop a different line of reasoning to prove that GK_n always contains many paths. Alternatively, it would be very interesting to find point sets which contain only few edge-disjoint plane spanning paths.

We also study packings of edge-disjoint planar spanning trees that have bounded vertex degree and bounded diameter. In particular, in Section 4 we show that for any $k \leq \sqrt{n/12}$ any set of n points has k edge-disjoint plane spanning trees with maximum vertex degree $O(k^2)$ and diameter $O(\log(n/k^2))$.

Related work. A classic related problem in extremal graph theory is the following. For general geometric graphs, what is the maximum number f(k,n)such that there exists a geometric graph G of n vertices and f(k,n) edges such that G contains no k disjoint edges? Erdős [11] showed that for all $n \geq 3$, f(2,n) = n, i.e., any geometric graph with n+1 edges contains a disjoint pair. For general k, Tóth and Valtr [21] gave the lower and upper bounds of $3/2(k-1)n-2k^2 \le f(k+1,n) \le k^3(n+1)$, and also showed that $4n-9 \le f(4,n) \le 8.5n$. Černý [8] proved $f(3,n) \le \lfloor 2.5n \rfloor$. More specifically, the existence of certain plane subgraphs has been investigated. Károlyi, Pach, and Tóth [14] showed that any edge 2-coloring of a complete geometric graph GK_n admits a monochromatic plane spanning tree. Černý et al. [9] also considered the existence of plane spanning trees in geometric graphs. They showed that after removing any set of at most $(1/2\sqrt{2})\sqrt{n}$ edges from any GK_n , the resulting graph still contains a plane spanning path. Aichholzer et al. [4] considered perfect matchings, subtrees and triangulations as plane subgraphs; further references to similar results can be found in [4]. For any geometric graph G, Rivera-Campo [19] showed that if any subgraph of G induced by five vertices has a plane spanning tree, then G as well has a plane spanning tree. Keller et al. [15] gave a characterization of the smallest subgraphs of any GK_n that share at least one edge with any plane spanning tree of GK_n (so-called blockers). They showed that if a subgraph G is a blocker for all plane spanning trees of diameter at most four, then G blocks all plane spanning subgraphs; if the vertices of GK_n are in convex position, the result already holds for a diameter of at most three.

Also the number of plane spanning trees attracted interest, analogously to classic results on the number of spanning trees (the tree density) in general graphs. Nash-Williams [17] and Tutte [22] independently showed that a graph G has a tree density of k if $|E_P(G)| \geq k(|P|-1)$ for every partition P of V(G), where $E_P(G)$ denotes the set of edges between different members of P. This was used by Kundu [16] to relate the tree density in general graphs to their edge-connectivity: any k-edge-connected graph has at least $\lceil k-1/2 \rceil$ edge-disjoint spanning trees.

Our problem is also closely related to the concept of k-book embeddings of

topological graphs, where, informally, the vertices are considered to be on the spine of a book and each edge of the graph is either on the spine or on exactly one of the k pages, such that no two edges cross. The book thickness of a graph G is the smallest number k for which there exists a k-book embedding of G. Bernhart and Kainen [6, Theorem 3.4] showed that, for $n \geq 4$ vertices, the book thickness of the complete graph is $\lceil n/2 \rceil$. Their construction of $\lfloor n/2 \rfloor$ edge-disjoint paths directly carries over to packing the same amount of plane spanning paths in the complete convex geometric graph [7].

A concept between graph-theoretical thickness and book thickness was later developed by Dillencourt, Eppstein, and Hirschberg [10]: given an abstract graph G, the geometric thickness of G is the smallest number k such that there exists a straight-line drawing of the graph that can be partitioned into k plane subgraphs. They showed that the geometric thickness of the (abstract) complete graph is between $\lceil (n/5.646) + 0.342 \rceil$ and $\lceil n/4 \rceil$.

Since the initial presentation of this work, the problem has attracted further attention. Most prominently, the lower bound on the number of plane edge-disjoint spanning trees has been improved to $\lfloor n/3 \rfloor$ by Garcia [12]. Schnider [20] considers the special case of double stars (i.e., trees with only two interior nodes),

showing that a partition into such trees does not always exist, and provides necessary as well as sufficient conditions for its existence.

2. Packing Spanning Trees

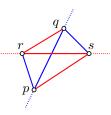
Recall that GK_n is the complete geometric graph on any set S of n points in general position in the plane.

Theorem 1. GK_n contains $\Omega(\sqrt{n})$ edge-disjoint plane spanning trees.

Proof. Let S be a set of n points in the plane, and let F be a set of k edges (pairs of points of S) such that each pair of edges in F has an interior crossing. The set F is called a *crossing family*.

We claim that there exists a set of k edge-disjoint plane spanning trees on S. We use a construction similar to the *double stars* by Bose et al. [7]. For each edge $e = \overline{pq} \in F$, let ℓ_e be the supporting line of e. We connect all points to the left of ℓ_e to p, and all points to the right of ℓ_e to q. These edges together with e form a tree T_e (see Figure 1).

To see that this yields k edge-disjoint trees, consider two trees $T_{\overline{pq}}$ and $T_{\overline{rs}}$. Suppose some edge is in both trees. Then one of its endpoints must be p or q, and the other endpoint must be r or s. However, if r lies to the left of $\ell_{\overline{pq}}$, then \overline{pr} and \overline{qs} are in $T_{\overline{pq}}$ and \overline{ps} and \overline{qr} are in $T_{\overline{rs}}$, and vice versa if r lies to the right of $\ell_{\overline{pq}}$.



Aronov et al. [5] showed that any set of n points contains a crossing family of size $\sqrt{n/12}$. The theorem follows immediately.

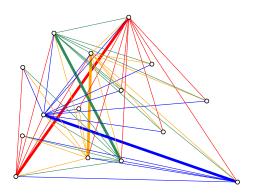


Figure 1: A set of 15 points with 4 pairwise crossing edges.

In a set of h points in convex position, there is always a crossing family of size $\lfloor h/2 \rfloor$. The proof of Theorem 1 therefore immediately implies the following.

Corollary 1. The complete graph of a set S of n points, of which h are in convex position, contains at least $\lfloor h/2 \rfloor$ edge-disjoint plane spanning trees.

Theorem 2. If $n \geq 4$ then GK_n contains at least 2 edge-disjoint plane spanning trees.

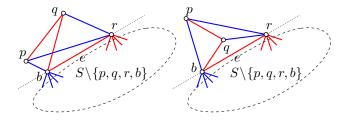


Figure 2: The two cases for constructing two edge-disjoint plane spanning trees on S.

Proof. Let S be a set of n points in the plane and let e = rb be an edge spanned by S having exactly 2 points (p and q) of S on one side (i.e., on one side of

the straight line supporting e). The set $\{p, q, r, b\}$ is either in convex position (Case 1; see Figure 2 (left)) or forms a triangle with one interior point (Case 2; see Figure 2 (right)). Note that e has to be an edge of the convex hull of $\{p, q, r, b\}$. W.l.o.g., let pqrb be the convex polygon in Case 1 and let q be the point inside the triangle prb in Case 2. In both cases we construct two edge-disjoint spanning trees on $\{p, q, r, b\}$, $\langle q, r, p, b \rangle$ (blue) and $\langle p, q, b, r \rangle$ (red). To get two edge-disjoint spanning trees on S we connect all points of $S \setminus \{p, q, r, b\}$ with S0 (for the blue tree) and with S1 (for the red tree).

Note that the proof of Theorem 1 also immediately implies Theorem 2 for $n \geq 5$, because then there always exists a pair of crossing edges in GK_n . For n = 4 the two cases for $\{p, q, r, b\}$ shown in Figure 2 serve as a proof.

Lemma 1. GK_6 contains 3 edge-disjoint plane spanning trees.

Proof. For n=6 there exist 16 combinatorially different point sets (order types) [3]. It is easy to check that each of these 16 cases allows for 3 edge-disjoint plane spanning trees packed on GK_6 (see Figure 8).

Using the order type database for small point sets [2] it can be easily checked that GK_8 and GK_9 each contain 4 edge-disjoint plane spanning trees, and that GK_{10} contains 5 edge-disjoint plane spanning trees. (The latter has been obtained by reducing the set of order types to so-called crossing-maximal ones, as characterized in [18].)

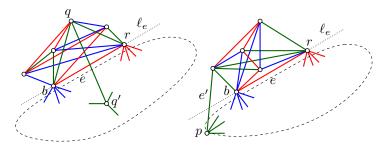
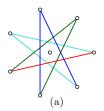
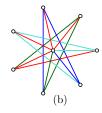
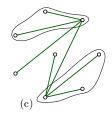


Figure 3: Two examples depicting the construction of three edge-disjoint plane spanning trees on S.

Theorem 3. If $n \ge 6$ then GK_n contains at least 3 edge-disjoint plane spanning trees.







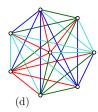


Figure 4: The graph GW_{2n} cannot have plane spanning paths if it is partitioned into plane spanning trees.

Proof. Let S be a set of n points in the plane and let e = rb be an edge spanned by S having exactly 4 points of S on one side (i.e., on one side of the straight line ℓ_e supporting e). Let S' be the set of 6 points containing r, b, and the exactly 4 points on one side of e. By Lemma 1, S' contains 3 edge-disjoint plane spanning trees. For simplicity we call them red, blue, and green. W.l.o.g., assume that e is part of the red tree. Note that each point of S' is incident to all three trees, and that r and b are extremal points for $S \setminus (S' \setminus \{r, b\})$. We construct a red and a blue plane spanning tree by connecting r and b, respectively, with all points in $S \setminus S'$.

Next we construct the third (green) plane spanning tree on S. Note that the green plane spanning tree on S' can be completed to a triangulation T. Let q be the point of $S' \setminus \{r, b\}$ such that qrb is a triangle in T. Observe that any edge incident to q and crossing e does not cross a green edge.

Assume that there exists a point $q' \in (S \setminus S')$ such that the edge qq' crosses e. Then we connect q and q' with a green edge and complete the green plane spanning tree by connecting all points in $S \setminus (S' \cup \{q'\})$ with q'. See Figure 3 (left).

If such a point q' does not exist, then there has to exist an edge e' of the convex hull of S, such that e' crosses ℓ_e . Denote by p the endpoint of e' in $S \setminus S'$. We color e' green and complete the green plane spanning tree by connecting all points in $S \setminus (S' \cup \{p\})$ with p. See Figure 3 (right).

3. Packing Spanning Paths

Let W_{2n} be a set of 2n points in the "regular wheel configuration" in the plane. W_{2n} consists of 2n-1 points regularly spaced on a circle C and a point at the center of C. Let GW_{2n} be the complete geometric graph on W_{2n} .

Theorem 4. GW_{2n} can be partitioned into n spanning trees. If $n \geq 3$ then none of these trees can be a path.

Proof. In the following, we color the edges of GW_{2n} that each class is plane and spanning. Let v_0 be the central vertex and let the other vertices be v_1, \ldots, v_{2n-1} in cyclic order. The complete graph has edges of varying length between the vertices v_1, \ldots, v_{2n-1} , and we can use E_1, \ldots, E_{n-1} to denote the length classes of the edges, from short to long. The edges involving v_0 are called the radial edges. There are 2n-1 edges in each length class and also 2n-1 radial edges.

We first consider the length class E_{n-1} , then the radial edges, and then E_{n-2}, \ldots, E_1 , and see how we must color these edges to produce plane spanning trees.

Given that there are 2n-1 edges in E_{n-1} , to be divided over n colors, and every non-adjacent pair of edges intersect, we will get these edges in n-1 pairs and one singleton, see Figure 4(a). Call the color of the singleton edge in E_{n-1} red. The pairs must be two adjacent edges (they have a shared vertex), forming a wedge with point v_0 in between and at least one point to each side of the wedge if there are at least six points. This immediately shows that all spanning trees with non-red color are not paths. To show that a red spanning tree also cannot be a path, we observe that v_0 can have at most one edge in each non-red color (otherwise we make a cycle or an intersection within that color). Therefore, it must have n incident red edges, showing that the red spanning tree is not a path either if $n \geq 3$ (Figure 4(b)).

We proceed to show that the geometric graph contains n plane spanning trees. We color the radial edges by using the red color n times. There are two options when we do not have crossings or cycles, and they are symmetric. The remaining radial edges get the other n-1 colors, one for each, and such that a path of length 3 appears in each color. Then we assign the edges in E_{n-2}, \ldots, E_1 a color at once. We make 2n-1 fans, one for each of v_1, \ldots, v_{2n-1} , consisting of one edge of each length class (there are two choices: clockwise and counterclockwise), see Figure 4(c) for the two fans of one color. Each fan can be assigned a color so that all spanning trees are isomorphic balanced double stars, completing the partitioning into n plane spanning trees (Figure 4(d)).

Interestingly, GW_{2n} contains n-1 plane spanning paths, via the zigzag

construction used for points in convex position (as described in [7]). When the path passes the center point, it picks it up using two radial edges instead of a long edge, see Figure 5. But to get one more plane spanning tree in GW_{2n} , all paths must be trees.

We now return to GK_n , the complete geometric graph on any set S of n points in general position in the plane.

Theorem 5. If $n \ge 4$ then GK_n contains at least 2 edge-disjoint plane spanning paths.

Proof. Let S be a set of n points in the plane and let p be an extremal point of S. Order the points of $S \setminus \{p\}$ clockwise around p. Partition $S \setminus \{p\}$ into two (disjoint) sets A and B, such that $A \cup B = S \setminus \{p\}$ and $|B| - 1 \le |A| \le |B|$. We denote by ℓ a line through p (but no other point of S) that is separating A from B (see Figure 6).

We will construct the two edge-disjoint paths, for simplicity call them red and blue. The red path $(\mathcal{R} = G(V, E_1))$ we simply construct as a plane zigzag path starting at p, with a point q in B as a second point, and with every edge of \mathcal{R} , except pq, intersecting l. (An algorithm for constructing such a zigzag path is described by Hershberger and Suri [13], see also Abellanas et al. [1].)

The blue path $(\mathcal{B} = G(V, E_2))$ consists of two subpaths, \mathcal{B}_A and \mathcal{B}_B , joined at p. Observe that no red edge (edge of \mathcal{R}) connects two points of $A \cup \{p\}$ or two points of B. Thus, any (blue) path completely contained in $A \cup \{p\}$ is edge-disjoint to \mathcal{R} . We choose the path starting at p and connecting the points of A in clockwise order around p for \mathcal{B}_A .

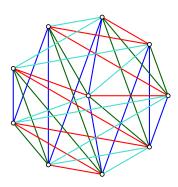


Figure 5: GW_{2n} contains n-1 plane spanning paths.

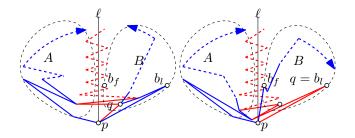


Figure 6: Partition of $S \setminus \{p\}$ and the two edge-disjoint spanning paths. Left: $q \neq b_l$. Right: $q = b_l$.

Let b_f and b_l be the first and last, respectively, point of B in clockwise order around p. If $q = b_l$ then we connect p with b_f and continue on the points of $B \setminus \{b_f\}$ in clockwise order around p for \mathcal{B}_B (see Figure 6 (right)). Otherwise, we construct \mathcal{B}_B with pb_l as the first edge and then finish the path by connecting the points of $B \setminus \{b_l\}$ in counter clockwise order around p (see Figure 6 (left)).

Connecting \mathcal{B}_A and \mathcal{B}_B at p results in the plane spanning path \mathcal{B} that is edge-disjoint to the plane spanning path \mathcal{R} .

4. Packing Spanning Trees with low Degree

The edge-disjoint plane spanning trees we studied in the previous sections are somehow extreme in terms of vertex degree. The trees constructed in Section 2 always contain at least one vertex of degree $\Omega(n)$, while in Section 3 we consider spanning paths. Thus the question arises if intermediate results are possible. In the following, we obtain a trade-off between the number of edge-disjoint spanning trees and the maximum degree of each vertex.

Theorem 6. For any set S of n points and $k \leq \sqrt{n/12}$ there exist k edge-disjoint plane spanning trees T_1, \ldots, T_k on S such that the maximum degree of any tree is in $O(k^2)$. Also, the diameter of each tree is in $O(\log(n/k^2))$.

Proof. The general idea of the proof is to "peel off" small clusters of points and connect each of the clusters with k edge-disjoint spanning trees independently. Consider a $(12k^2-2)$ -edge, i.e., an edge uv, u, $v \in S$, such that exactly $12k^2-2$ points of S are strictly to the left of the directed line ℓ through uv. Consider the set C_1 of these $12k^2$ points and construct k edge-disjoint plane spanning trees of C_1 using Theorem 1. Now consider the midpoint between u and v. Let ℓ' be

a line through that midpoint that splits the remaining point set $S \setminus C_1$ into two subsets S_u and S_v , each containing at most $\lceil (n-12k^2)/2 \rceil$ points.

Since the two subsets are separated by ℓ' , we can recursively repeat a similar process in the two subsets independently. That is, pick a $(12k^2-2)$ -edge u'v' of $S_u \cup \{u\}$ such that u is contained among the $12k^2$ points separated by u'v' but is not an endpoint of the edge (such an edge must always exist). We construct k plane spanning trees on this subset, which are connected to the spanning trees of C_1 via u. We treat $S_v \cup \{v\}$ analogously (see Figure 7). The recursion stops when we are not able to partition the remaining points into two sets of size at least $12k^2-1$; here, we simply add the remaining points of the subset to the last cluster. Note that this cluster must have between $12k^2$ and $36k^2-3$ points, thus we can still create k edge-disjoint spanning trees using Theorem 1.

We construct the k spanning trees of S by assigning one of the spanning trees of each cluster arbitrarily to each of the trees T_1, \ldots, T_k . We claim that the resulting trees are indeed spanning: By construction, each tree is spanning in the cluster; hence points of the same cluster will be connected in T_i (for all $i \leq k$). Moreover, the hierarchical construction certifies that each cluster shares a point with the cluster constructed in the previous step of induction. Likewise, planarity of each tree is guaranteed.

We obtain at most $N = \lfloor n/(12k^2 - 1) \rfloor$ clusters which are arranged such that they form a balanced binary tree with C_1 as root. Note that the spanning trees constructed in the proof of Theorem 1 have diameter 3. Thus, the diameter of each spanning tree is at most $6 \lceil \log_2 N \rceil$. The degree bound follows from the

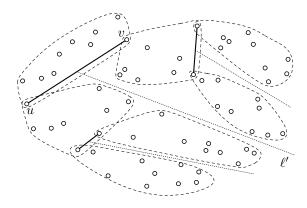


Figure 7: The hierarchical clustering strategy.

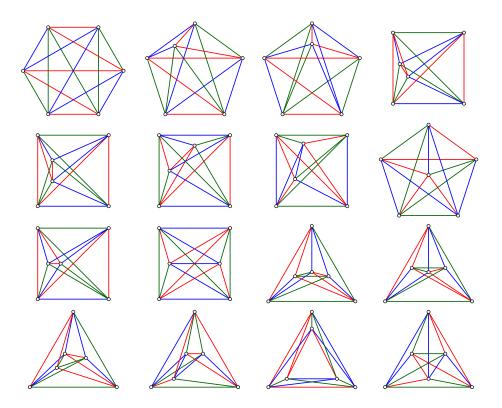


Figure 8: The 16 combinatorially different point sets for n=6 [3, 2], with 3 edge-disjoint plane spanning trees each.

fact that any point of S can only belong to at most two clusters (and each cluster has $\Theta(k^2)$ points).

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